

# **A Robust Detector for Pedestrian Detection**

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## Introduction

We proposes a robust detector especially for pedestrian detection. Considering the diversity of the dataset, we use a series of powerful methods to enhance the robustness of our model. Since there exists various sizes of persons in the images, we adopt FPN[1] to extract features from different levels. Due to the mAP evaluation metric, localization performance is very important, so we perform cascaded detection like Cascade R-CNN[2]. For better feature extraction, we use some useful modules like Deformable Convolution[3], Re-weighting pooled features[4], ROI-Align[5], etc. Moreover, context information is encoded in the features for occlusion handling. For robustness, we use data augmentations like changing gamma, changing saturation, gaussian blur and random cropping. Multi-scale testing and ensemble are used for better results.

# Data Analysis

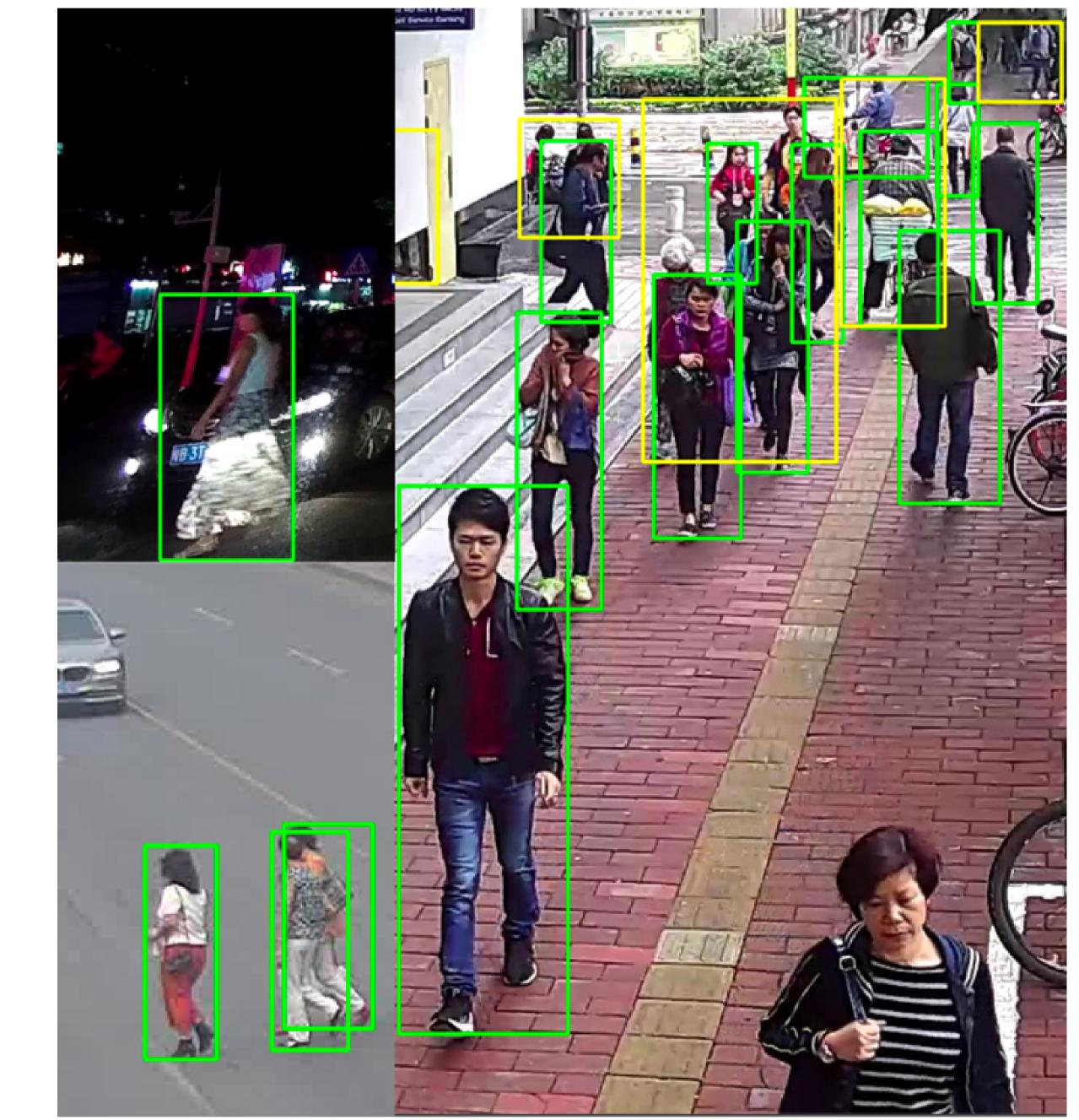
Since data is extremely important to the network's performance, we first did data

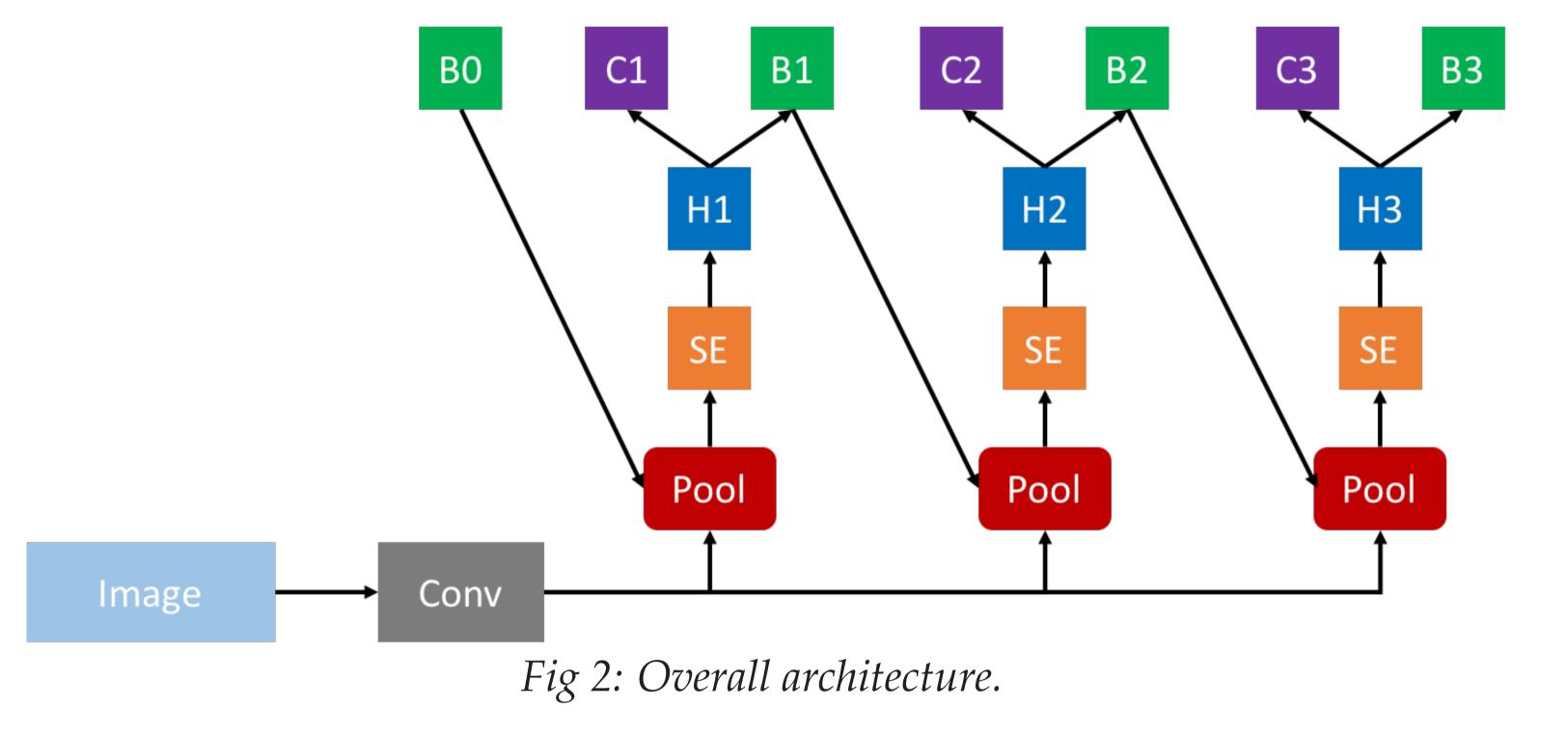
# Architecture

**Overall Architecture:** 

analysis. There are several cases which can be seen from *Fig* 1:

- Different brightness and scenes
- Various sizes of persons
- Occlusion
- Unlabelled persons





#### **Basemodel:**

- We use Resnet-50[6] since it's a very powerful and popular basemodel
- Deformable Convolution[3] is used for better feature extraction, especially for occlusion handling

## FPN with Cascade R-CNN:

- FPN[1] is adopted to handle different scales of person
- Cascade R-CNN[2] helps to achieve more accurate localization performance, since localization is very important in the AP metric

## Fig 1: Wider Pedestrian Data Analysis.

In the image, green boxes represent ground-truth boxes, yellow boxes are ignored boxes. We are able to find that the woman in the lower right corner is not labelled, and the two persons in the lower left corner have a big overlap. And it is obviously that there are different scenes and various sizes of persons. These are the challenges of this dataset.

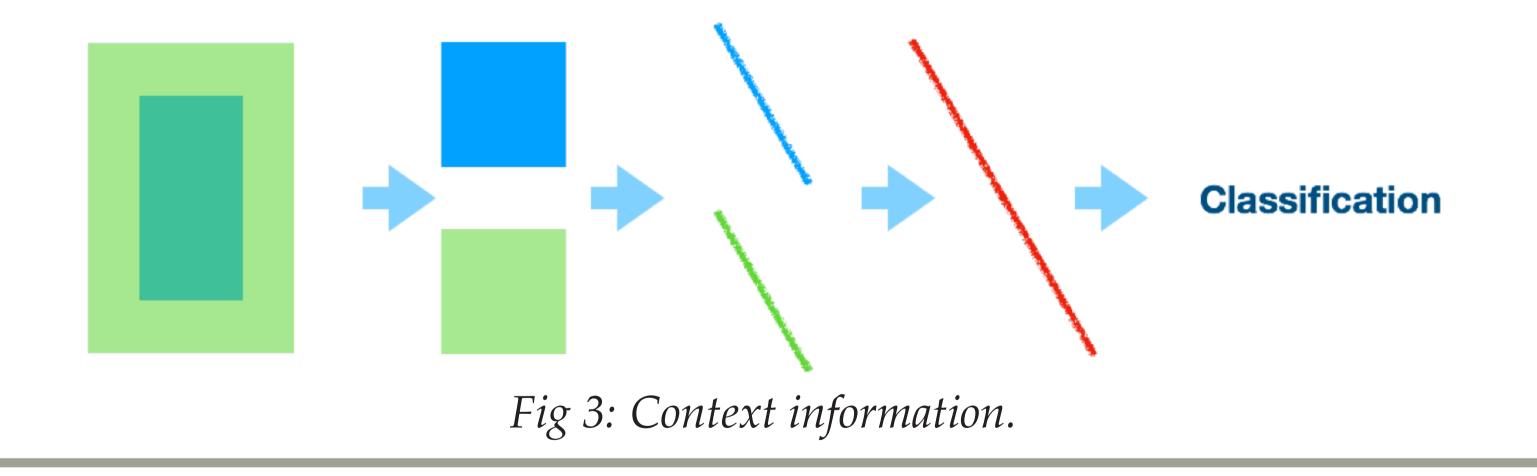
# Training and Testing

#### **Training:**

- Data augmentation: change gamma, saturation, gaussian blur, random crop, etc.
- Multi label: regarding pedestrian and cyclist as different labels.
- Multi scale testing(4 scales with flipped): we merge the results from different

#### **Useful modules:**

- ROI-align[5] uses bilinear interpolation instead of quantization when pooling features, this get more precise features
- Re-weight Pool5[4] adds an channel-wise attention after pooled features to focus on important channels. It is useful for occlusion handling
- Context information: We concatenate the FCs for better classification performance as in *Fig 3*



Results			
Method	Comments	AP	
Cascade RCNN	3 stage [0.5, 0.6, 0.7]	+3.8	

scales, adopt soft-nms[7] and do box-voting.

• Ensemble: we split the network into RPN-net and RCNN-net, select proposals from the result of all RPN-nets, send them into RCNN-net to get the results form different models, then normalize scores and coordinates.

#### References

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Reweight Pool5-+0.8Multi labelspecify person and cyclist+0.4Augmentationcolor and random crop+3.5Bn training-+1.3Multi-scale testing4 scale with flip+2.9Ensemble4 models+2.2Single Res-501st submission, full image training63.21Single SE-152[9]2nd submission, full image training66.573 model Ensemble3rd submission, random crop training68.725 model Ensemble4th submission, random crop training69.566 model Ensembleadd a Crowd Human[8] pre-trained model69.63JDAI-Human-64.4NtechLab-62.49	Deformable conv	-	+0.8
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